



## Logical Methods: Fault Tree

Prof. Francesco Di Maio  
Dipartimento di Energia  
Via La Masa 34, B12

[francesco.dimaio@polimi.it](mailto:francesco.dimaio@polimi.it)



# System representation

# (complex) System representation

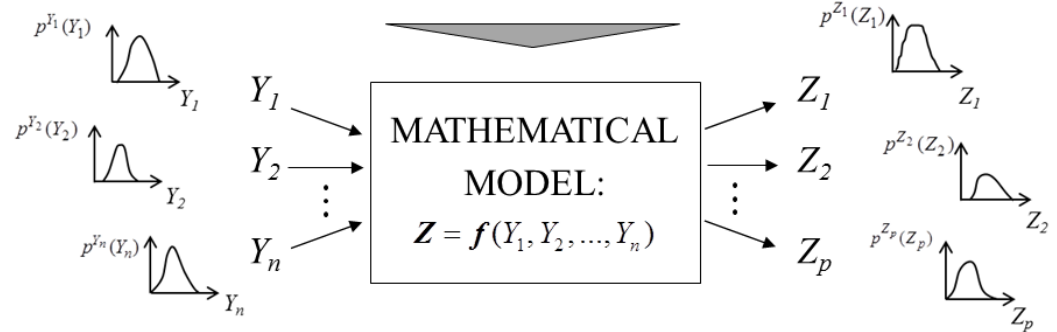
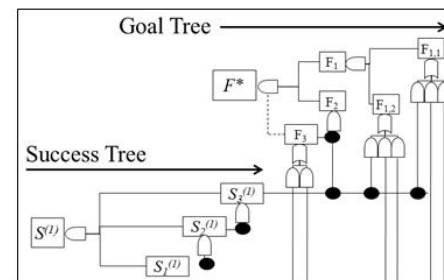
Definition of the structural, logical and functional relations among the components of the system



REAL SYSTEM



REPRESENTATION



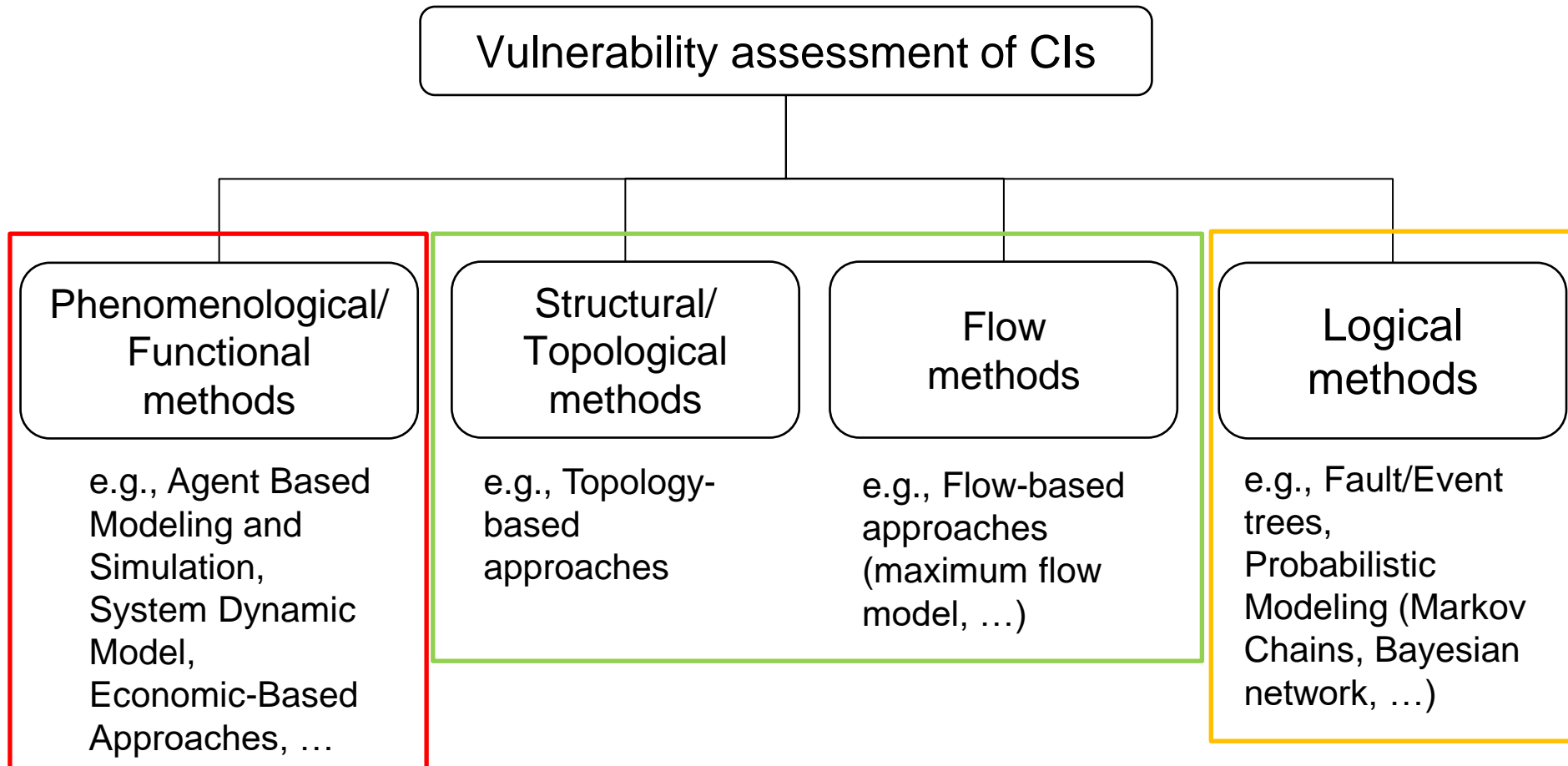
SIMULATION with UNCERTAINTY PROPAGATION



# System representations in the scientific literature

Three main types of system representation techniques exist:

- Phenomenological/Functional methods
- Graph structure
  - Structural methods
  - Flow methods
- Hierarchical
  - Logical methods (e.g., Fault Tree / Event Tree, Goal Tree Success Tree + (Dynamic) Master Logic Diagram)





Logical methods are:

- **apt to representation;**
- capable of capturing the **logic of the functioning/dysfunctioning** of a complex system;
- capable of identifying the **combinations of failures of elements** (hardware, software, and human and organization), which lead to the **loss of the system-of-systems function.**



# Logical Methods: Fault Tree



# Objectives

1. Decompose the system failure in elementary failure events of constituent components
2. Computation of system failure probability, from component failure probabilities

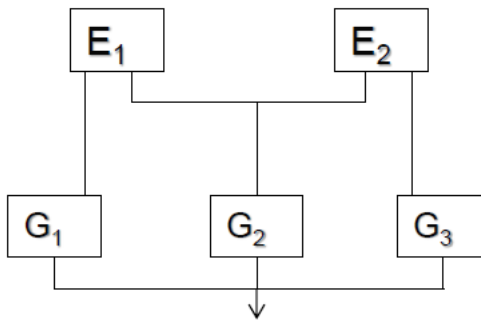




- Systematic and quantitative
- Deductive (search for causes)

## 1. Define top event (system failure)

Electrical generating system



E1, E2 = engines

G1, G2, G3 = generators, each one is rated at 30 KVA

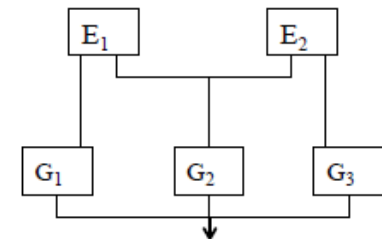
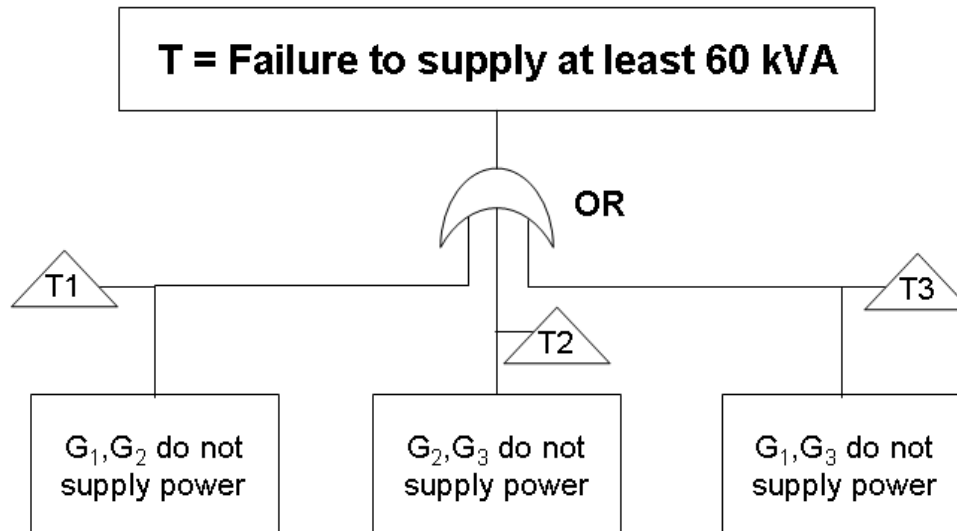


**T = Failure to supply at least 60 kVA**

# FT construction: Procedure steps

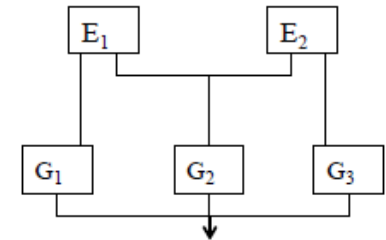
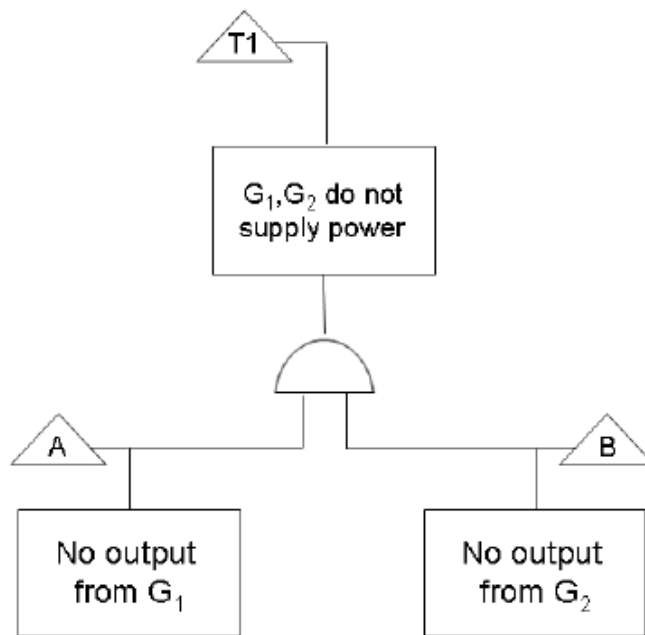
1. Define top event (system failure)
2. **Decompose top event by identifying sub-events which can cause it.**

At least two out of the three generators do not work



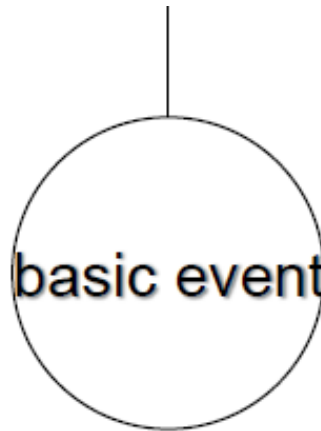
# FT construction: Procedure steps

1. Define top event (system failure)
2. Decompose top event by identifying subevents which can cause it.
3. **Decompose each subevent in more elementary subevents which can cause it**



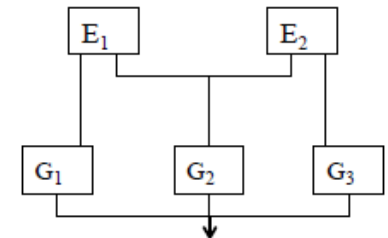
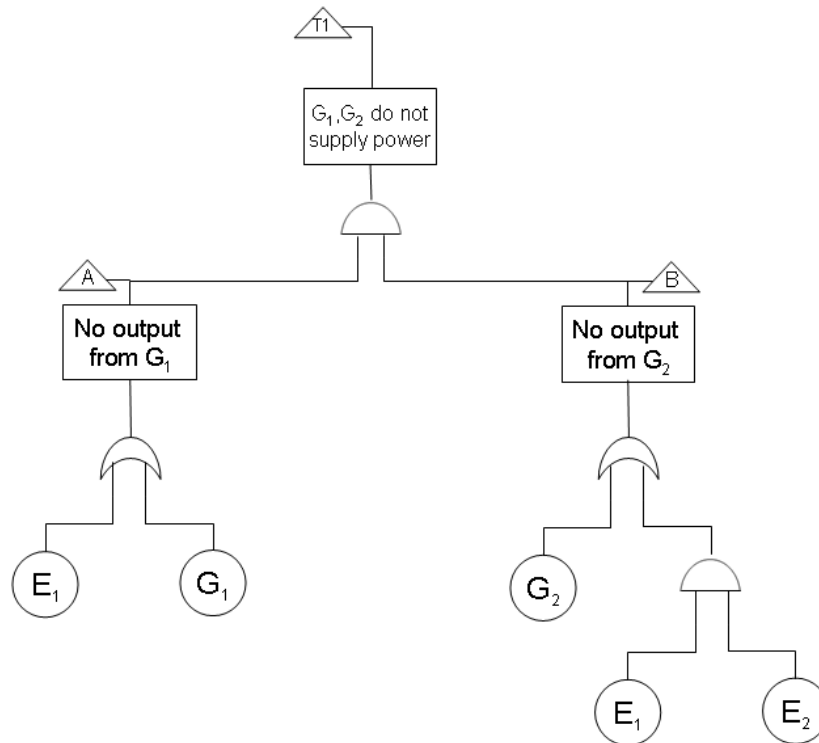
## FT construction: Procedure steps

1. Define top event (system failure)
2. Decompose top event by identifying subevents which can cause it.
3. Decompose each subevent in more elementary subevents which can cause it
4. **Stop decomposition when subevent probability data are available (resolution limit): subevent = basic or primary event**



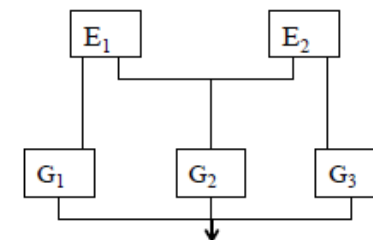
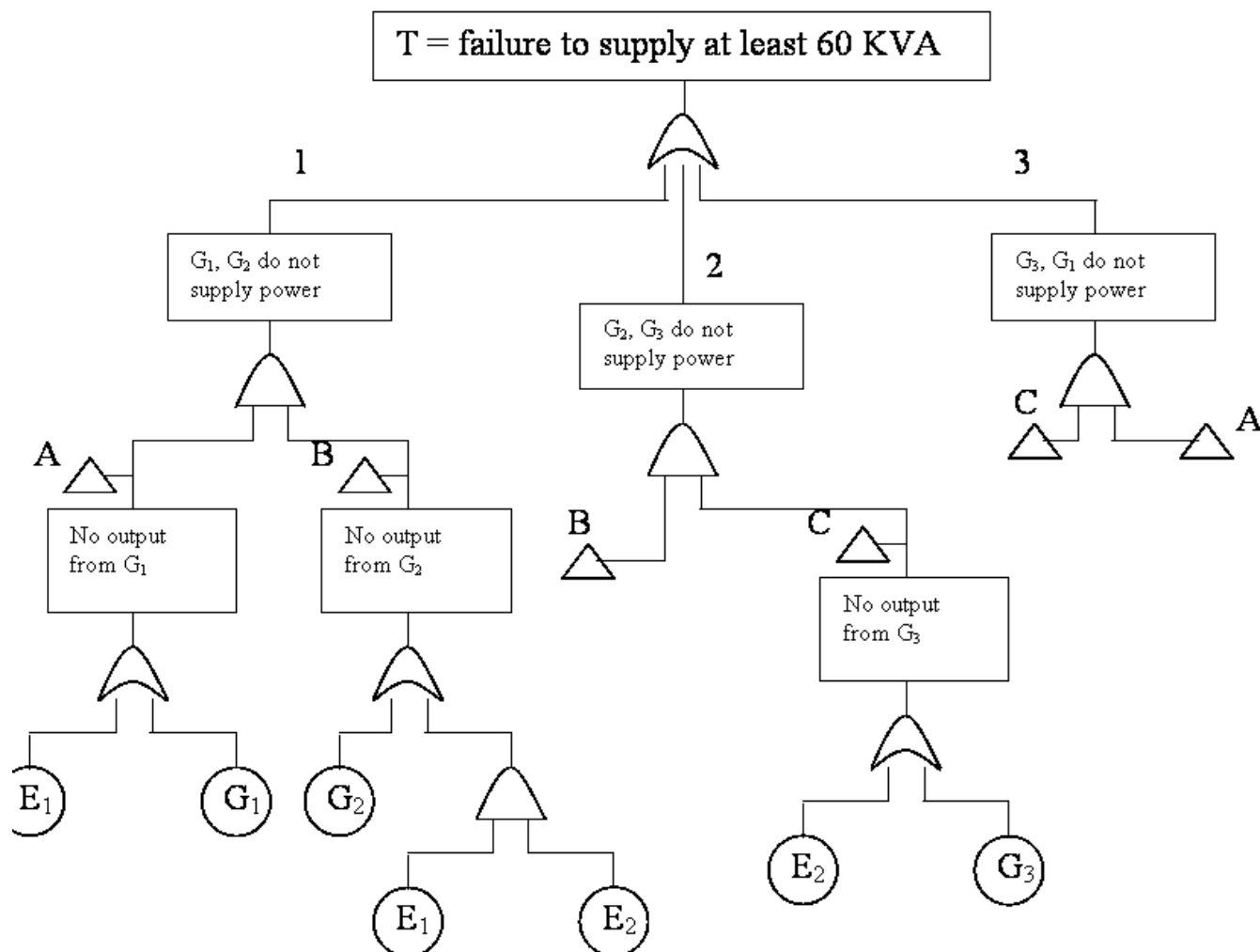
# FT construction: Procedure steps

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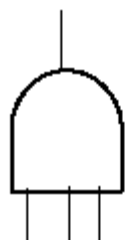


# FT example 1





## FT gate symbols



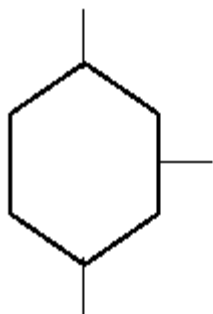
**AND gate**

**Output event occurs if all input events occur simultaneously.**



**OR gate**

**Output event occurs if any one of the input events occurs.**



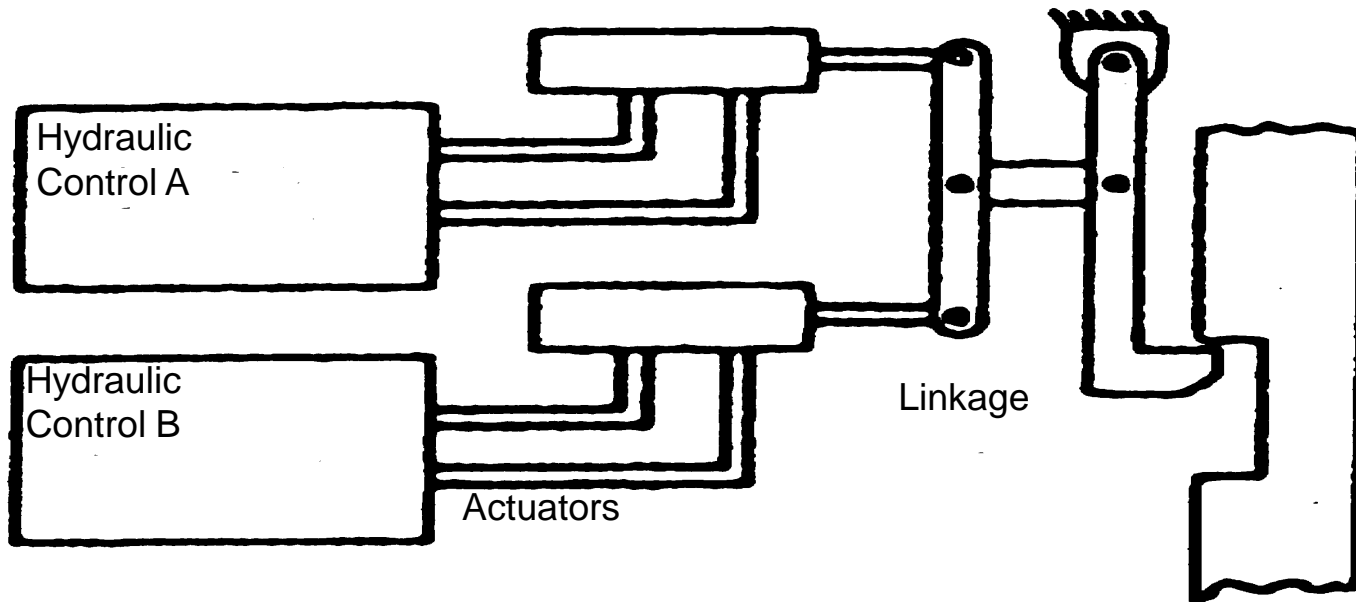
**Inhibit gate**

**Input produces output when conditional event occurs.**





## FT Example 2: The System





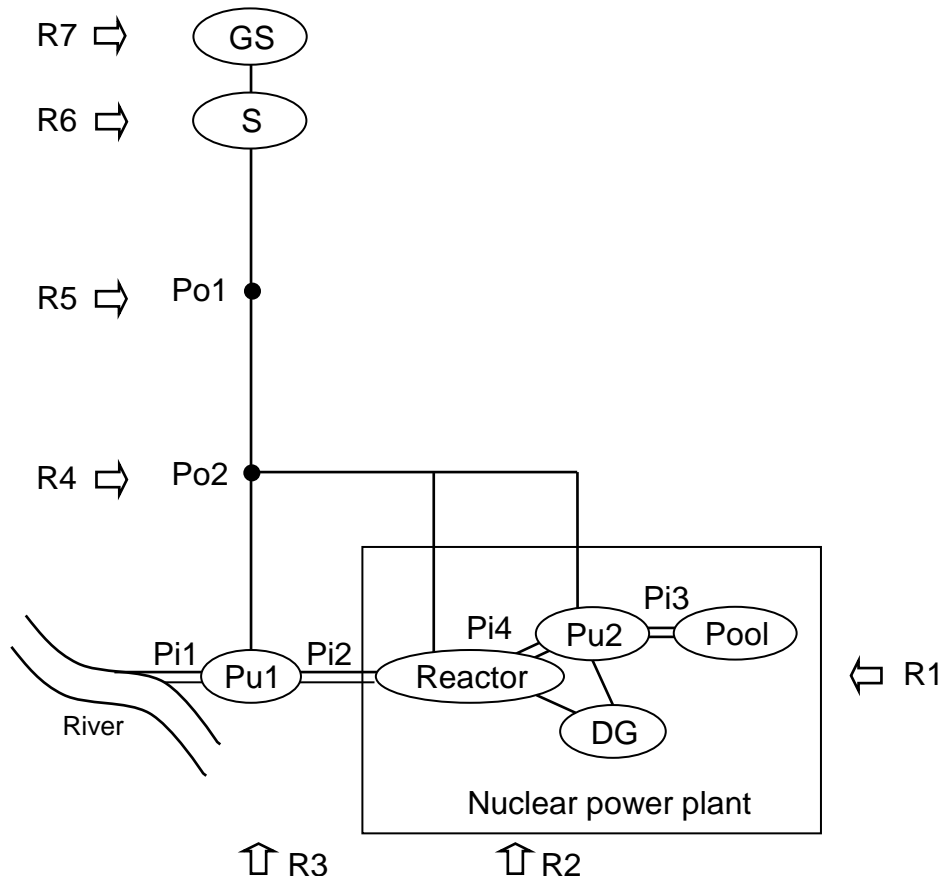
# FT Example 3: The System of Systems

## Internal emergency devices:

- Power system  
Diesel Generator (DG)
- Water system  
Pipe (Pi)  
Pump (Pu)  
Pool

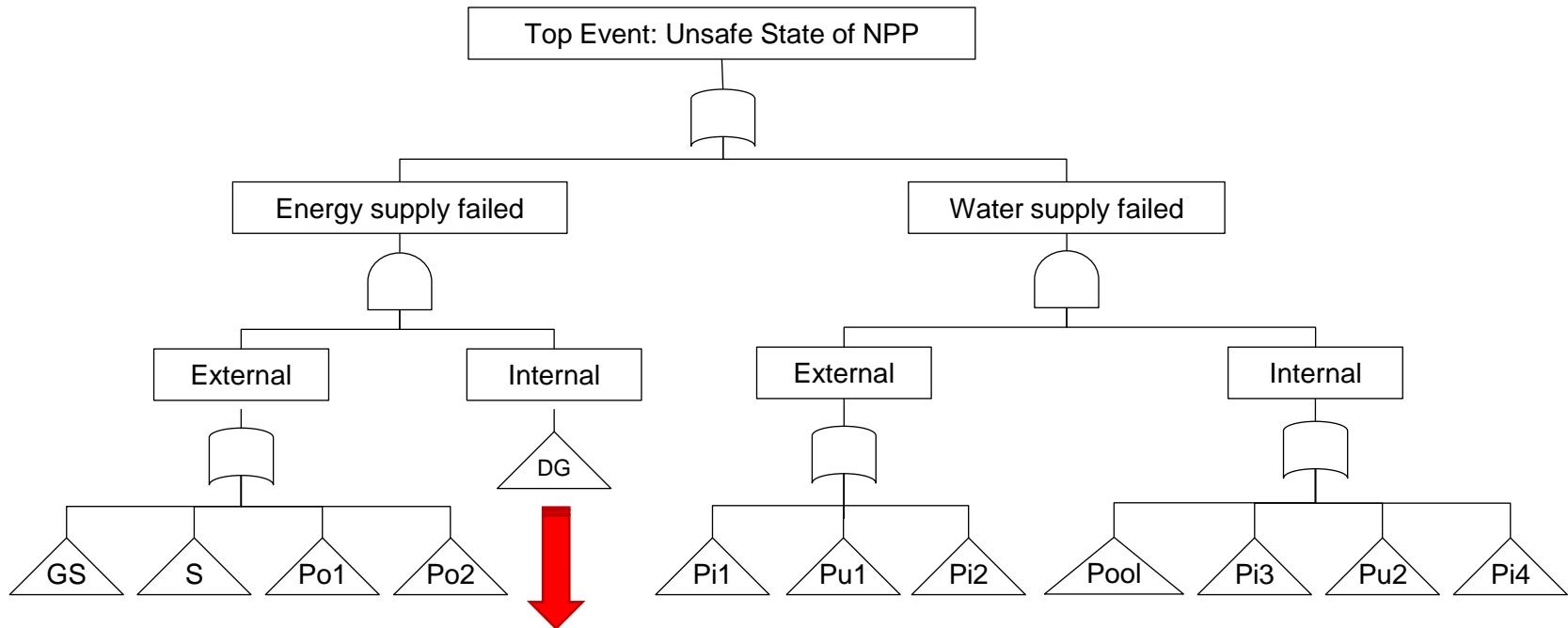
## Interdependent CIs:

- Power system  
Generation Station (GS)  
Substation (S)  
Pole (Po)
- Water system  
Pipe (Pi)  
Pump (Pu)  
River
- Road transportation system  
Road access (R)

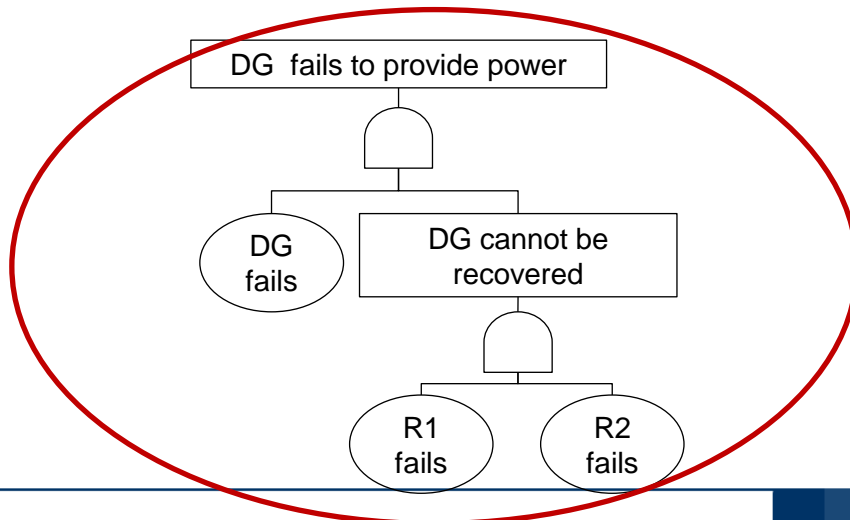




# FT Example 3: Fault Tree



Example:



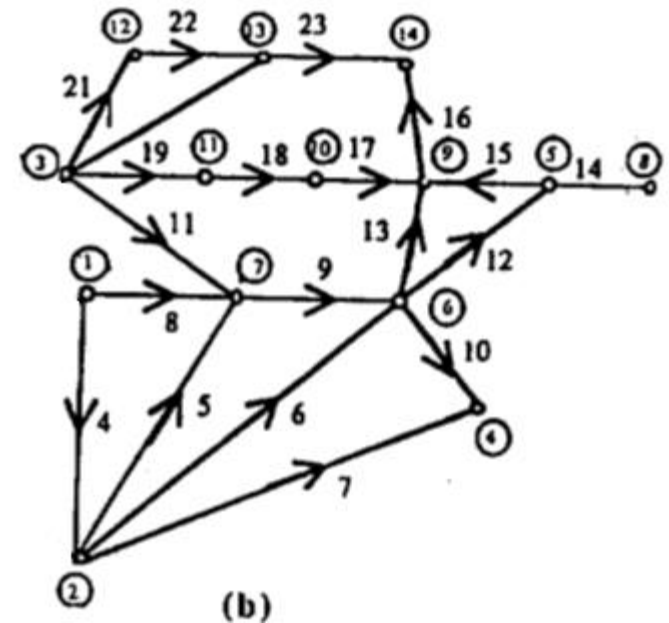
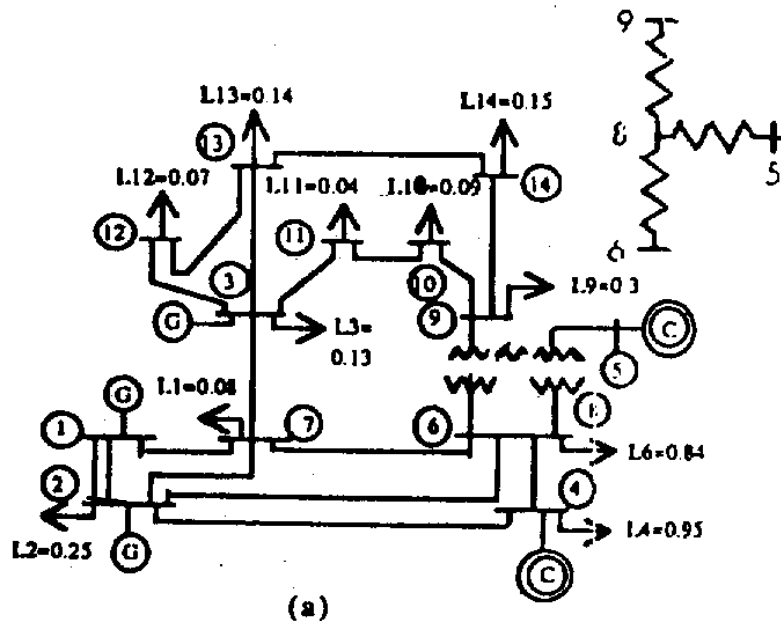
Hp: elements that fail can be immediately repaired/replaced if the access through the road system does not fail → roads considered as “reserve components”.


# FT Example 4: IEEE14 Bus Power Distribution System

Generators (G1, G2 , G3)

Loads (2, 3, 4, 6, 7, 9, 10, 11, 12, 13, 14)

Power delivery paths: lines (L) and buses (B).





## FT Example 4: IEEE14 Bus Power Distribution System

Draw a Fault Tree (FT) for the top event “failure to supply power Load2”

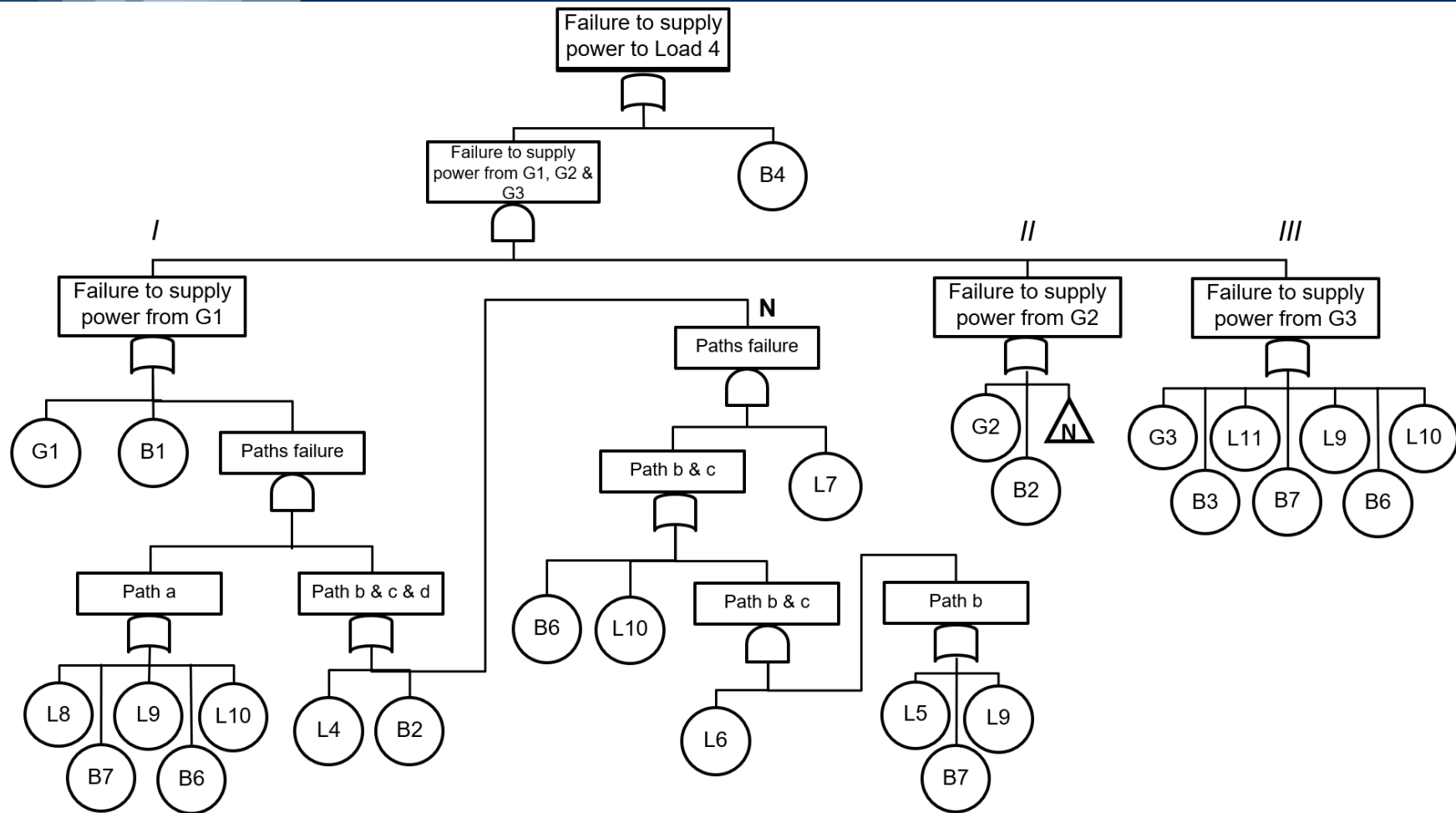


## FT Example 4: IEEE14 Bus Power Distribution System

Draw a Fault Tree (FT) for the top event “failure to supply power Load4”



# FT Example 4: IEEE14 Bus Power Distribution System





# FT qualitative analysis





- Introducing:
- $X_i$  : binomial indicator variable of  $i$ -th component state (basic event)

$$X_i = \begin{cases} 1 & \text{failure event true} \\ 0 & \text{failure event false} \end{cases}$$

- **FT = set of Boolean algebraic equations (one for each gate)  $\Rightarrow$  structure (switching) function  $\Phi$ :**

$$X_T = \Phi (X_1 , X_2 , \dots , X_n)$$



# Boolean Logic laws

## 1) Commutative Law:

- (a)  $XY = YX$
- (b)  $X + Y = Y + X$

## 2) Associative Law

- (a)  $X(YZ) = (XY)Z$
- (b)  $X + (Y + Z) = (X + Y) + Z$

## 3) Idempotent Law

- (a)  $XX = X$
- (b)  $X + X = X$

## 4) Absorption Law

- (a)  $X(X + Y) = X$
- (b)  $X + XY = X$

## 5) Distributive Law

- (a)  $X(Y + Z) = XY + XZ$
- (b)  $(X + Y)(X + Z) = X + YZ$

## 6) Complementation\*

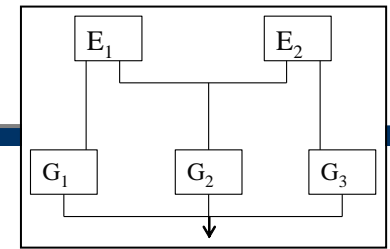
- (a)  $X\bar{X} = \emptyset$
- (b)  $X + \bar{X} = \Omega$
- (c)  $\bar{\bar{X}} = X$

## 7) Unnamed relationships but frequently useful

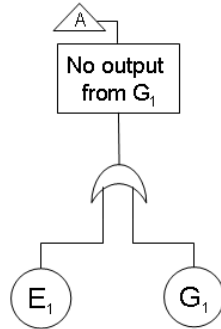
- (a)  $X + \bar{X}Y = X + Y$
- (b)  $\bar{X}(X + Y) = \bar{X}\bar{Y}$



# Structure function: Example 1

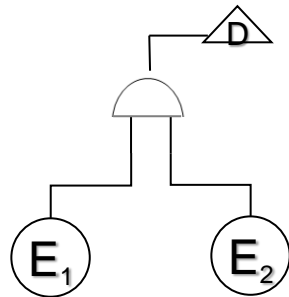


OR gate

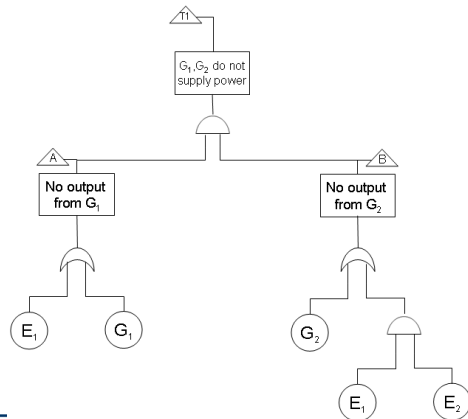


$$\begin{aligned} X_A &= X_{E_1} + X_{G_1} - X_{E_1} X_{G_1} = \\ &= 1 - (1 - X_{E_1})(1 - X_{G_1}) \end{aligned}$$

AND gate



$$X_D = X_{E_1} X_{E_2}$$



$$X_{T_1} = \Phi(X_{E_1}, X_{E_2}, X_{G_1}, X_{G_2})$$



Structure functions can be expressed in reduced expressions in terms of minimal path or cut sets.

A path set is a set  $\underline{X}$  such that  $\Phi(\underline{X}) = 0$ ;

a cut set is a set  $X$  such that  $\Phi(X) = 1$ .

Physically, a path (cut) set is a set of components whose functioning (failure) ensures the functioning (failure) of the system.

### ■ Reduce $\Phi$ in terms of minimal cut sets (mcs)

- **cut sets** = logic combinations of primary events which render true the top event
- **minimal cut sets** = cut sets such that if one of the events is not verified, the top event is not verified

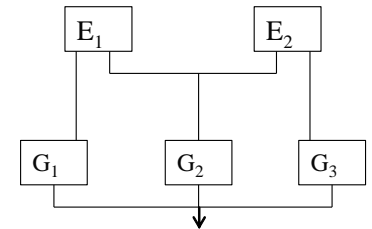


- FT = set of boolean algebraic equations (one for each gate) => structure (switching) function  $\Phi$ :

$$X_T = \Phi(X_1, X_2, \dots, X_n)$$

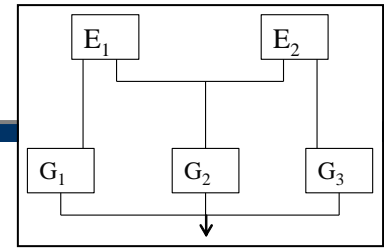
- Boolean algebra to solve FT equations

$$\begin{aligned} X_{T_1} &= X_A X_B = \\ &= (X_{E_1} + X_{G_1} - X_{E_1} X_{G_1})(X_{G_2} + X_{E_1} X_{E_2} - X_{E_1} X_{E_2} X_{G_2}) = \\ &= X_{E_1} X_{G_2} + X_{E_1} X_{E_2} - X_{E_1} X_{E_2} X_{G_2} + X_{G_1} X_{G_2} + X_{E_1} X_{E_2} X_{G_1} + \\ &\quad - X_{E_1} X_{E_2} X_{G_1} X_{G_2} - X_{E_1} X_{G_1} X_{G_2} - X_{E_1} X_{E_2} X_{G_1} + X_{E_1} X_{E_2} X_{G_1} X_{G_2} = \\ &= X_{E_1} X_{G_2} + X_{E_1} X_{E_2} + X_{G_1} X_{G_2} - X_{E_1} X_{E_2} X_{G_2} - X_{E_1} X_{G_1} X_{G_2} \end{aligned}$$





## mcs: Example 1



$$X_{T_1} = X_{E_1} X_{G_2} + X_{E_1} X_{E_2} + X_{G_1} X_{G_2} - X_{E_1} X_{E_2} X_{G_2} - X_{E_1} X_{G_1} X_{G_2}$$

$$= 1 - [1 - X_{E_1} X_{G_2} - X_{E_1} X_{E_2} - X_{G_1} X_{G_2} + X_{E_1} X_{E_2} X_{G_2} + X_{E_1} X_{G_1} X_{G_2}] =$$

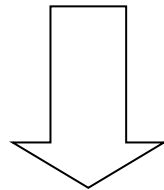
$$= 1 - [1 - X_{E_1} X_{G_2} - X_{E_1} X_{E_2} - X_{G_1} X_{G_2} + X_{E_1} X_{E_2} X_{G_2} + X_{E_1} X_{G_1} X_{G_2} + X_{E_1} X_{E_2} X_{G_1} X_{G_2} - X_{E_1} X_{E_2} X_{G_1} X_{G_2}] =$$

$$= 1 - [1 - X_{E_1} X_{E_2} - X_{G_1} X_{G_2} + X_{E_1} X_{E_2} X_{G_1} X_{G_2} - X_{E_1} X_{G_2} + X_{E_1} X_{E_2} X_{G_2} + X_{E_1} X_{G_1} X_{G_2} - X_{E_1} X_{E_2} X_{G_1} X_{G_2}] =$$

$$= 1 - [1 - X_{E_1} X_{E_2} - X_{G_1} X_{G_2} + X_{E_1} X_{E_2} X_{G_1} X_{G_2} - X_{E_1} X_{G_2} (1 - X_{E_1} X_{E_2} - X_{G_1} X_{G_2} + X_{E_1} X_{E_2} X_{G_1} X_{G_2})] =$$

$$= 1 - [(1 - X_{E_1} X_{G_2})(1 - X_{E_1} X_{E_2} - X_{G_1} X_{G_2} + X_{E_1} X_{E_2} X_{G_1} X_{G_2})] =$$

$$= 1 - [(1 - X_{E_1} X_{G_2})(1 - X_{E_1} X_{E_2})(1 - X_{G_1} X_{G_2})]$$



3 minimal cut sets:

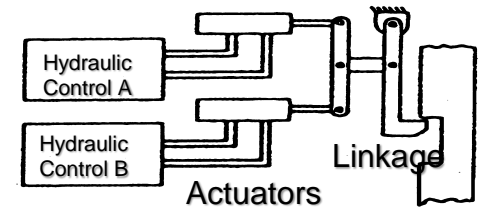
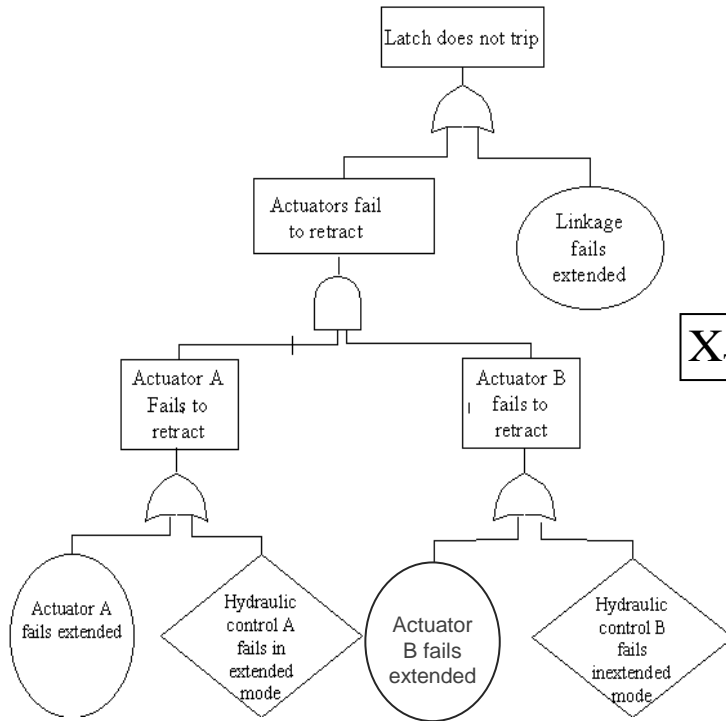
$$M_1 = \{E_1 G_2\}$$

$$M_2 = \{E_1 E_2\}$$

$$M_3 = \{G_1 G_2\}$$



## mcs: Example 2



$$X_T = 1 - (1 - X_L)(1 - (X_A + X_{HA} - X_A X_{HA}))(X_B + X_{HB} - X_B X_{HB}))$$

5 minimal cut sets:

$$M_1 = X_L$$

$$M_2 = X_A X_B$$

$$M_3 = X_A X_{HB}$$

$$M_4 = X_{HA} X_B$$

$$M_5 = X_{HA} X_{HB}$$



- 1. mcs identify the component basic failure events which contribute to system failure**
- 2. qualitative component criticality: those components appearing in low order mcs or in many mcs are most critical**

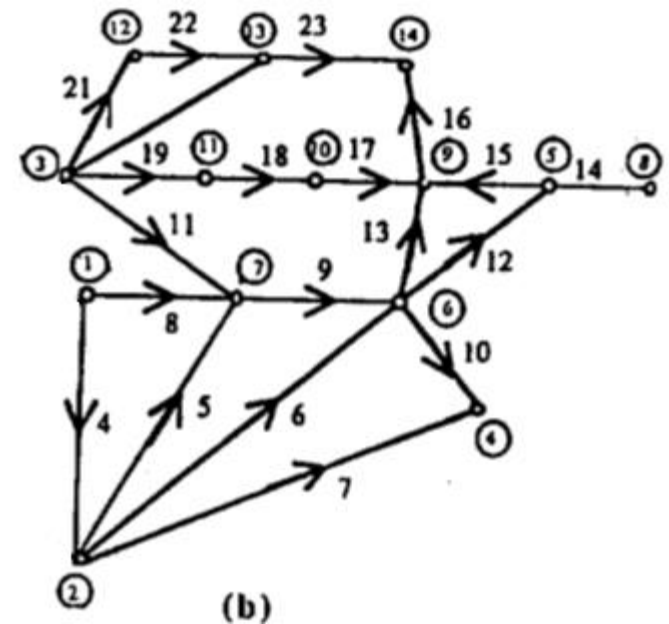
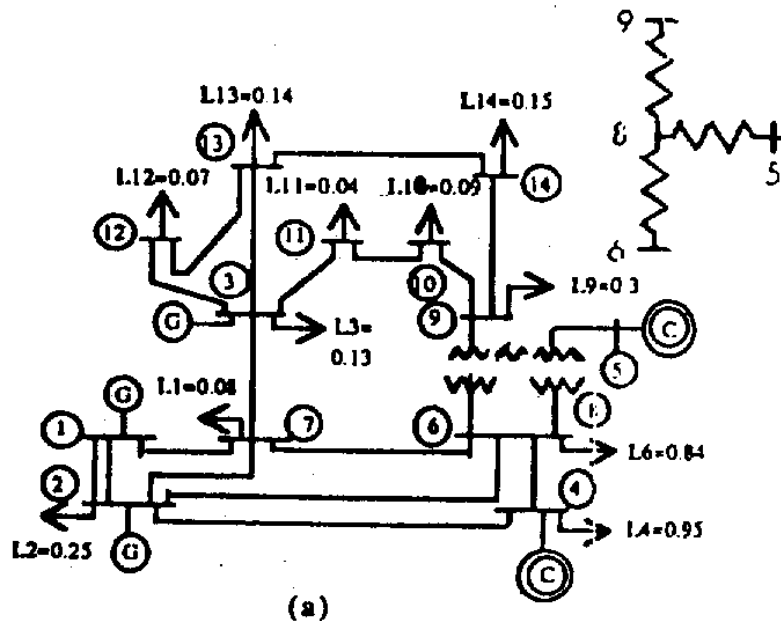


# FT Example 4: IEEE14 Bus Power Distribution System

Generators (G1, G2 , G3)

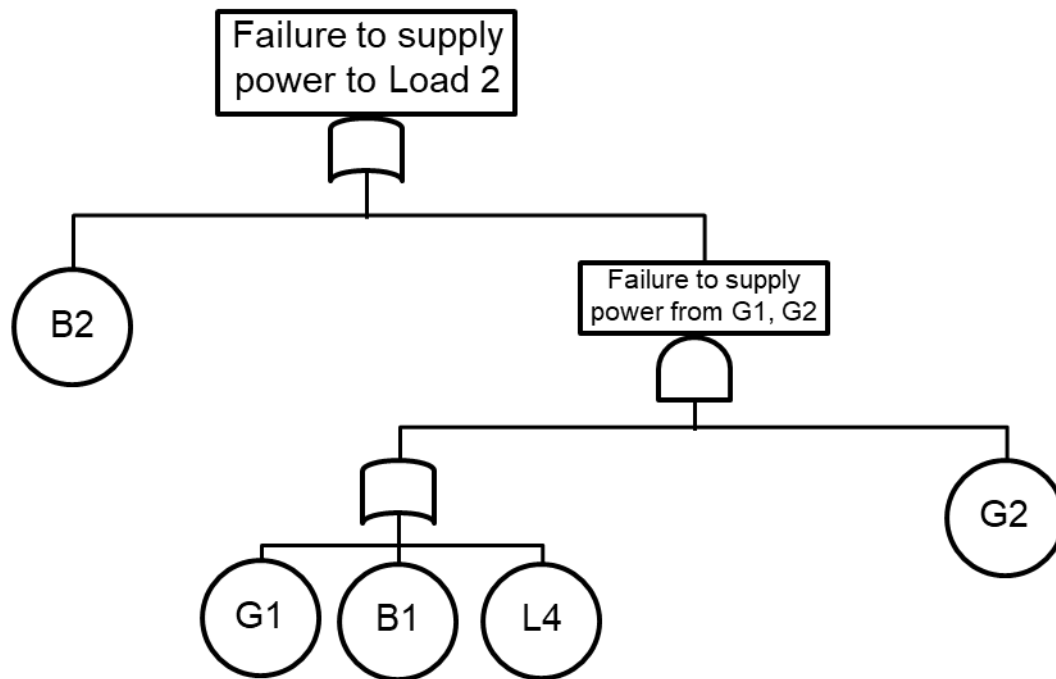
Loads (2, 3, 4, 6, 7, 9, 10, 11, 12, 13, 14)

Power delivery paths: lines (L) and buses (B).



# FT Example 4: IEEE14 Bus Power Distribution System

Find the Mcs for the top event “failure to supply power Load 2”



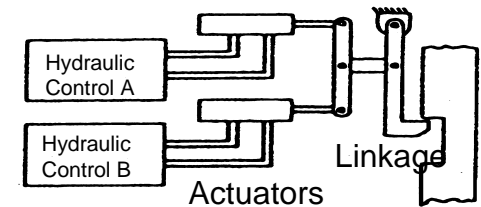
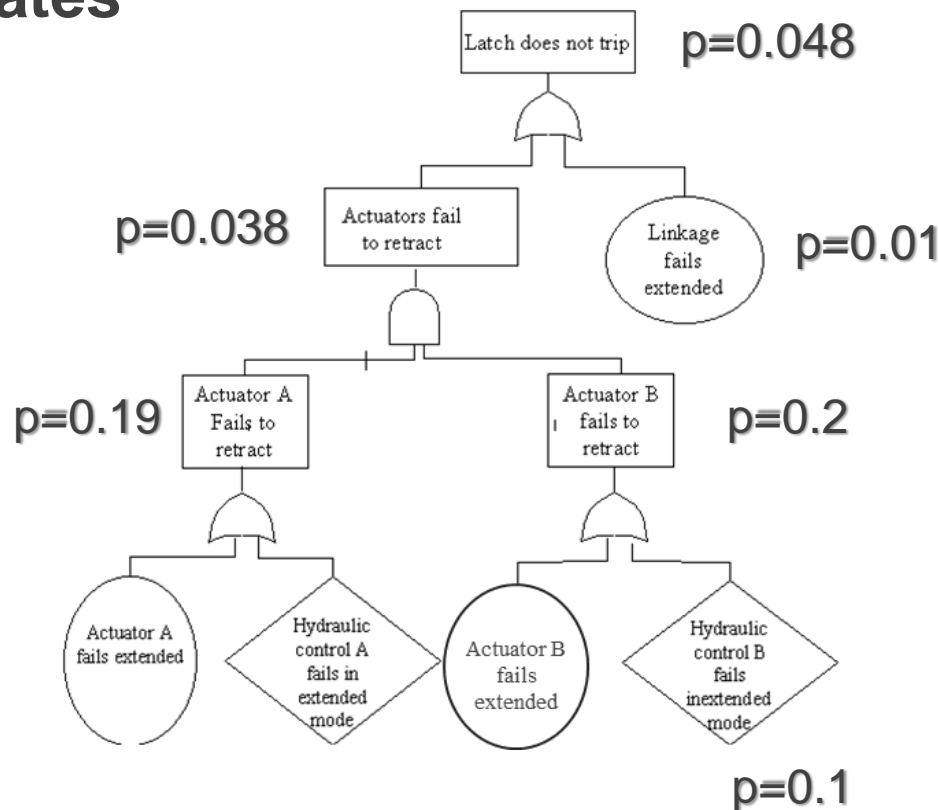


# FT quantitative analysis



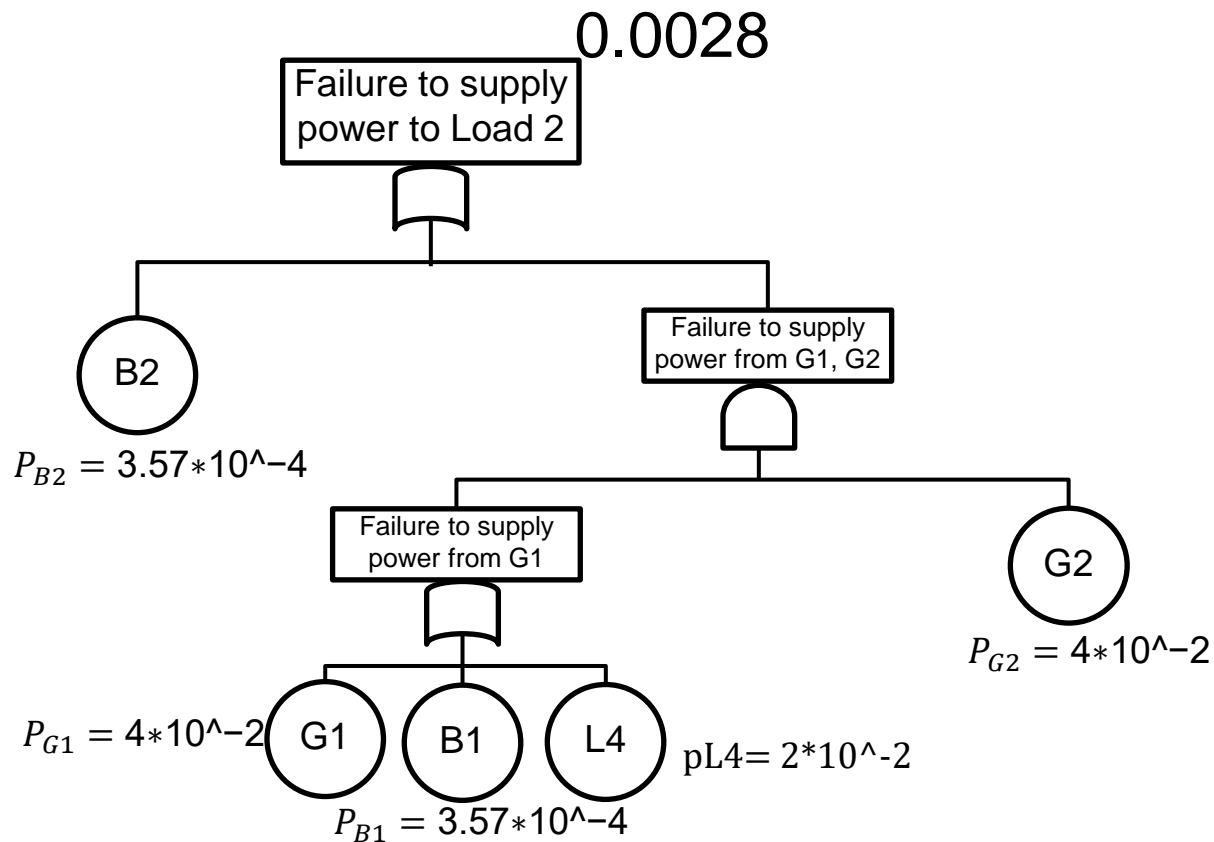
Compute system failure probability from primary events probabilities by:

## 1. using the laws of probability theory at the fault tree gates



# FT Example 4: IEEE14 Bus Power Distribution System

1. using the laws of probability theory at the fault tree gates





Compute system failure probability from primary events probabilities by:

1. using the laws of probability theory at the fault tree gates
2. **using the mcs found from the qualitative analysis**

$$P[\Phi(\underline{X}) = 1] = \sum_{j=1}^{mcs} P[M_j] - \sum_{i=1}^{mcs-1} \sum_{j=i+1}^{mcs} P[M_i M_j] + \cdots + (-1)^{mcs+1} P\left[\prod_{j=1}^{mcs} M_j\right]$$

**It can be shown that:**

$$\sum_{j=1}^{mcs} P[M_j] - \sum_{i=1}^{mcs-1} \sum_{j=i+1}^{mcs} P[M_i M_j] \leq P[\Phi(\underline{X}) = 1] \leq \sum_{j=1}^{mcs} P[M_j]$$



## FT quantitative analysis: Example 2

5 mcs:

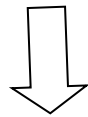
$$P(M_1) = P(X_L=1) = 0.01$$

$$P(M_2) = P(X_A X_B=1) = 0.1 \cdot 0.1 = 0.01$$

$$P(M_3) = P(X_A X_{HB}) = 0.1 \cdot 0.1 = 0.01$$

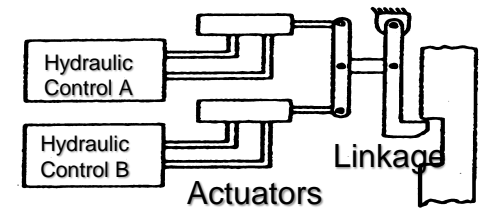
$$P(M_4) = P(X_{HA} X_B=1) = 0.1 \cdot 0.1 = 0.01$$

$$P(M_5) = P(X_{HA} X_{HB}) = 0.1 \cdot 0.1 = 0.01$$



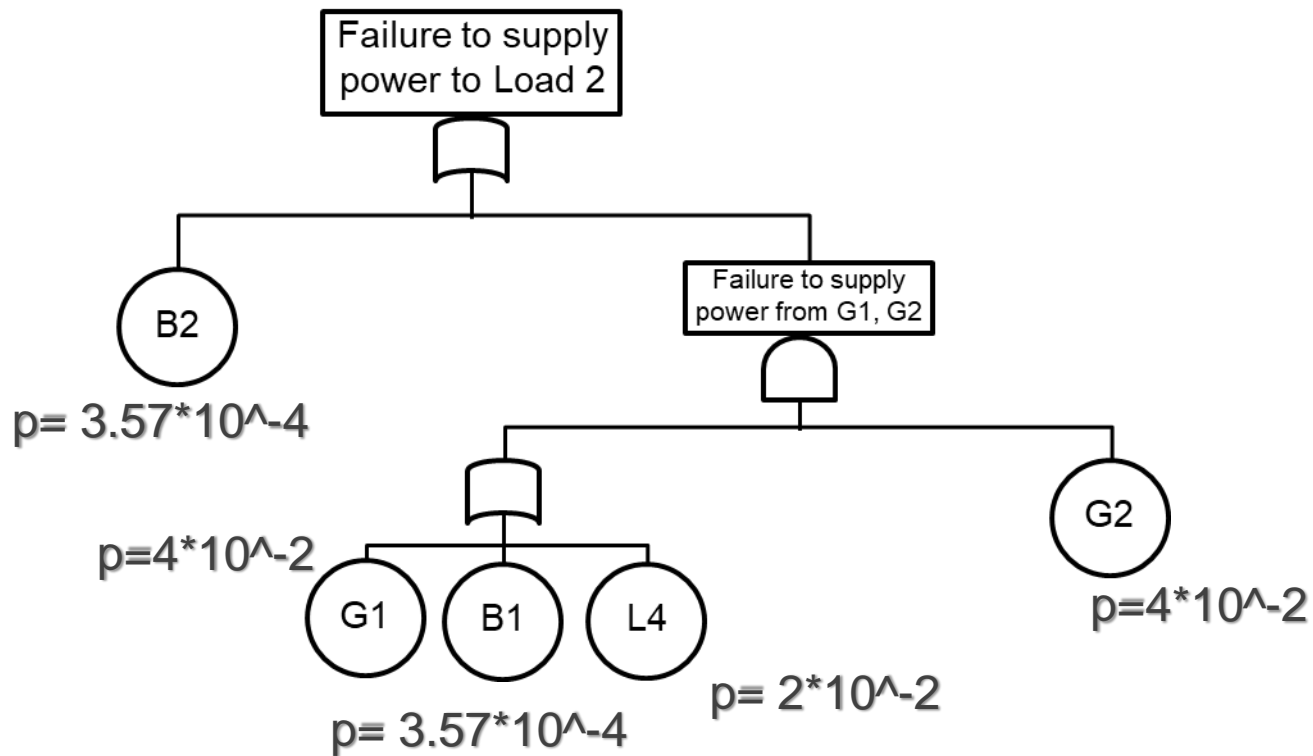
$$P[\Phi(\underline{X}) = 1] \leq \sum_{j=1}^{mcs} P[M_j] = 0.05$$

$$P[\Phi(\underline{X}) = 1] \geq \sum_{j=1}^{mcs} P[M_j] - \sum_{i=1}^{mcs-1} \sum_{j=i+1}^{mcs} P[M_i M_j] = 0.0464$$



# FT Example 4: IEEE14 Bus Power Distribution System

Find the Mcs for the top event “failure to supply power to bus 2” (Load2)







```
%%%%%%%% case 14bus %%%%%%%%%
```

```
branch_R=[0.999 0.9971 0.9980 0.9800 0.9908 0.8651 0.8634 0.8492 0.8333 0.9636  
0.8651 0.9998 0.9998 0.9998 1 1 0.8655 0.9536 0.9005 0.8974];
```

```
% Failure probability for power generation bus, load bus and transmission  
% bus.
```

```
P_bus=3.57*10^-4;
```

```
L_bus=2.33*10^-5;
```

```
bus=3*10^-5;
```

```
% Generator failure probability
```

```
Gen=4*10^-2;
```

```
%%%%%%%%%%%%LOAD2
```

```
% Components identified in mcs for Load2
```

```
B2=P_bus; G1=Gen; G2=Gen; B1=P_bus; L4=1-branch_R(4);
```

```
% mcs
```

```
M_1=B2;
```

```
M_2=G1*G2;
```

```
M_3=B1*G2;
```

```
M_4=L4*G2;
```

```
%Probability of failure of Load2
```

```
XT_Load2= 1-(1-M_1)*(1-M_2)*(1-M_3)*(1-M_4)=0.0028
```



1. Straightforward modelization via few, simple logic operators.
2. Physical elements represented in a well-defined structure, according to the logic of the system that leads to the identification of the minimal cut sets.
3. Minimal cut sets are a synthetic result which identifies the critical components.
4. Providing a graphical communication tool whose analysis is transparent.
5. Providing an insight into system behaviour.



1. Additional factors (operational, organizational, etc.) are not included. The exhaustive identification and manipulation of the minimal cut sets can be difficult for large systems.
2. Difficult to build the FT (in particular , in the case of large number of components and complicated logic dependencies).
3. No flexibility: the addition of a new component can change the entire structure of the FT.
4. No accounting for the strength of the relationships (Boolean-logic).